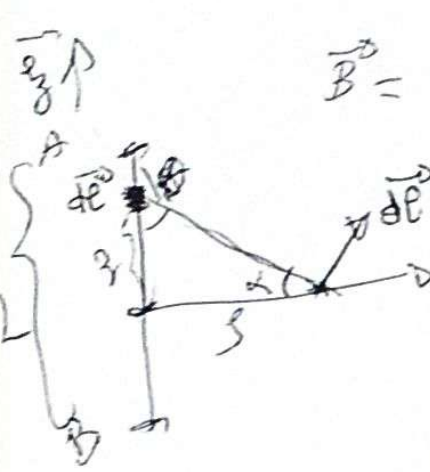


حل النموذج الثاني لقياس الكهرومغناطيسية



$\vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l} \times \vec{r}}{r^3}$ (1P) ت = 0.1 : لدرجات

$d\vec{l} = dz \vec{e}_3$; $\cos \alpha = \frac{r}{\rho} \Rightarrow r = \frac{\rho}{\cos \alpha}$

$d\vec{l} \times \vec{r} = dz r \sin \theta \vec{e}_\theta$

$\sin \theta = \cos \alpha$ $\Leftarrow \theta = \frac{\pi}{2} + \alpha$ (2P)

$\Rightarrow \vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{dz r \sin \theta}{r^3} \vec{e}_\theta = \frac{\mu_0 I}{4\pi} \int \frac{dz \cos \alpha}{\frac{\rho^2}{\cos^2 \alpha}} \vec{e}_\theta$

$\tan \alpha = \frac{\rho}{z} \Rightarrow z = \rho \tan \alpha$; $dz = \frac{\rho}{\cos^2 \alpha} d\alpha$

$\Rightarrow dz = \frac{\rho d\alpha}{\cos^2 \alpha}$

$\Rightarrow \vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{\rho / \cos \alpha d\alpha}{\frac{\rho^2}{\cos^2 \alpha}} \vec{e}_\theta = \frac{\mu_0 I}{4\pi} \int_{\alpha_1}^{\alpha_2} \frac{\cos \alpha d\alpha}{\rho} \vec{e}_\theta$ (1P)

$\Rightarrow \vec{B}(M) = \frac{\mu_0 I}{4\pi \rho} [\sin(\alpha_2) - \sin(\alpha_1)] \vec{e}_\theta$ (1P)

$\sin \alpha_1 = \frac{L/2}{\sqrt{(\frac{L}{2})^2 + \rho^2}}$; $\sin \alpha_2 = \frac{-L/2}{\sqrt{(\frac{L}{2})^2 + \rho^2}}$

بذلك يكون A و B ، لان اللانهاية

$\left. \begin{array}{l} A \rightarrow +\infty \Rightarrow \alpha \rightarrow \frac{\pi}{2} \\ B \rightarrow -\infty \Rightarrow \alpha \rightarrow -\frac{\pi}{2} \end{array} \right\} \Rightarrow \vec{B}(M) = \frac{\mu_0 I}{4\pi \rho} [1 - (-1)] \vec{e}_\theta$

$\Rightarrow \vec{B}(M) = \frac{\mu_0 I}{2\pi \rho} \vec{e}_\theta$ (1P)

3- كتابة حقل \vec{B} باستخدام قانون أمبير
 لدينا

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \Sigma I$$

$$\Rightarrow B \cdot 2\pi r = \mu_0 I$$

$$\Rightarrow B = \frac{\mu_0 I}{2\pi r}$$

$$\vec{B} = \frac{\mu_0 I}{2\pi r} \vec{e}_\phi$$

$$\vec{B} = B_0 \cos(\omega t - ky) \vec{u}$$

- اتجاه الانتشار هو (oy)
 - سرعة الانتشار ω/k

$$\lambda = \frac{\omega}{k} \Rightarrow k = \frac{\omega}{\lambda}$$

- اتجاه حقل \vec{B} هو (ox)
 - اتجاه حقل \vec{E} هو (oz)

$$\text{rot } \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\Rightarrow \vec{E} = \frac{1}{\mu_0 \epsilon_0} \int \text{rot } \vec{B} dt$$

$$\text{rot } \vec{B} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ B_x & 0 & 0 \end{vmatrix} = -\frac{\partial B_x}{\partial x} \vec{k} + \frac{\partial B_x}{\partial z} \vec{i}$$

$$\text{rot } \vec{B} = -B_0 k \sin(\omega t - ky) \vec{k}$$

$$\Rightarrow \vec{E} = \frac{1}{\mu_0 \epsilon_0} \int -B_0 k \sin(\omega t - ky) \vec{k} dt$$

$$\vec{E} = \frac{B_0 k}{\mu_0 \epsilon_0 \omega} \sin(\omega t - ky) \vec{k}$$